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Riemannian Geometry of Contact and Symplectic Manifolds, Second Edition provides new material in most chapters, but a particular emphasis remains on contact manifolds. New principal topics include a complex geodesic flow and the accompanying geometry of the projectivized holomorphic tangent bundle and a complex version of the special directions discussed in Chapter 11 for the real case.

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Alternative Title: elliptic geometry. Riemannian geometry, also called elliptic geometry, one of the non- Euclidean

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geometries that completely rejects the validity of Euclid's fifth postulate and modifies his second postulate. Simply stated, Euclid's fifth postulate is: through a point not on a given line there is only one line parallel to the given line.

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Riemannian geometry is the branch of differential geometry that studies Riemannian manifolds, smooth manifolds with a Riemannian metric, i.e. with an inner product on the tangent space at each point that varies smoothly from point to point. This gives, in particular, local notions of angle, length of curves, surface area and volume. From those, some other global quantities can be derived by integrating local contributions. Riemannian geometry originated with the vision of Bernhard Riemann expres

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The study of Riemannian geometry is rather meaningless without some basic knowledge on

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Gaussian geometry i.e. the geometry of curves and surfaces in 3-dimensional Euclidean space. For this we recommend the following text: M. P. do Carmo, Differential geometry of curves and surfaces, Prentice Hall (1976).

An Introduction to Riemannian Geometry
"The guiding line of this by now classic introduction to Riemannian geometry is an in-depth study of each newly introduced concept on the basis of a number of reoccurring well-chosen examples The book continues to be an excellent choice for an introduction to the central ideas of Riemannian geometry."

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